

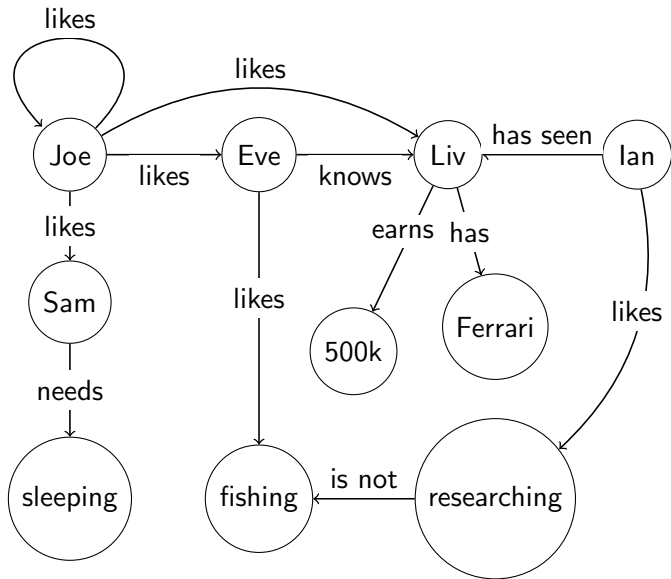
Querying Best Paths in Graph Databases

Jakub Michaliszyn, Jan Otop, Piotr Wieczorek

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December 14, 2017

Graph Databases

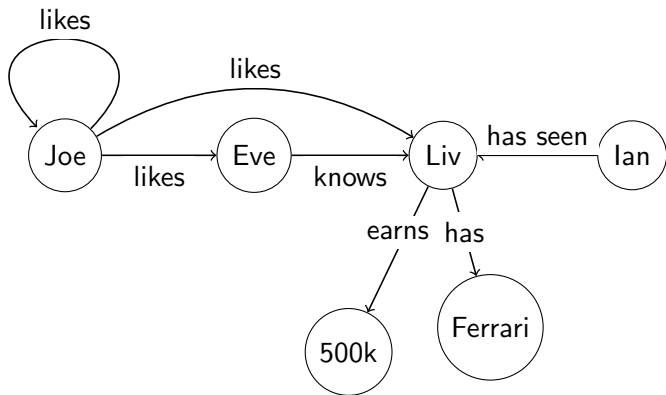


Regular Path Queries

$$x \rightarrow^{\pi} y \wedge ((\text{likes} + \text{knows})^* \cdot \text{has})(\pi)$$

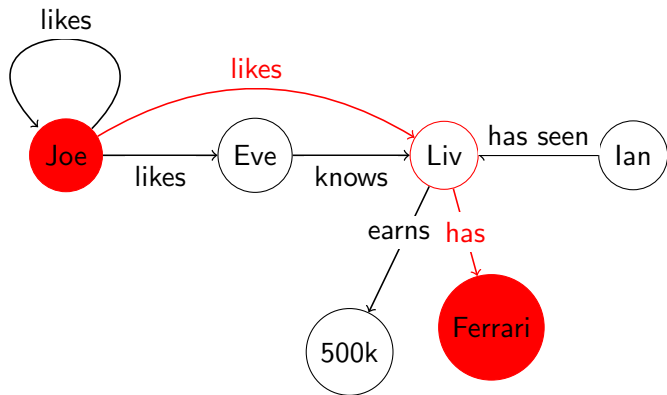
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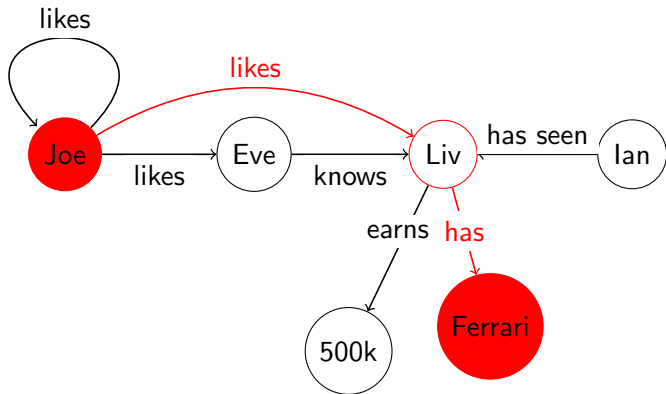
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Evaluation

- ▶ PSPACE-complete (combined complexity)
- ▶ NL-complete (data complexity)

Extensions of RPQs

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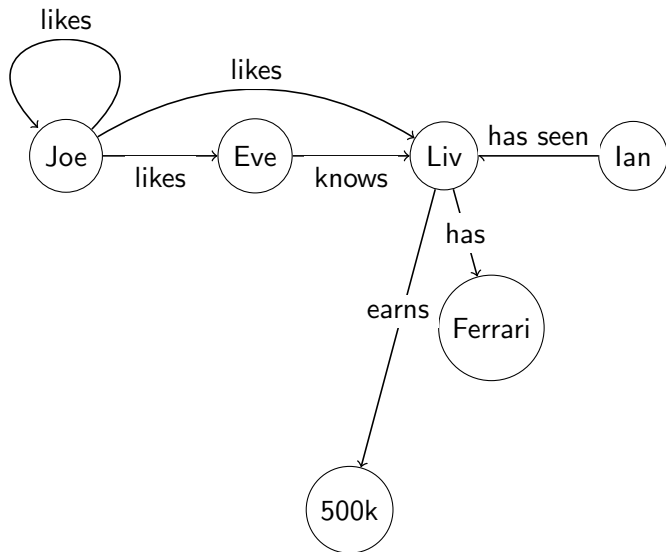
Extensions of RPQs

- ▶ conjunctions of RPQs, inverses,
- ▶ comparing paths: ECRPQs (regular relations), +linear constraints (Barcelo, Libkin, Lin, Wood),
- ▶ data values (properties)?
 - ▶ register automata and regular queries with memory (Vrigoč and Libkin)
 - ▶ LARE (arithmetical regular expressions) (Graboń, Michaliszyn, Otop, Wieczorek)

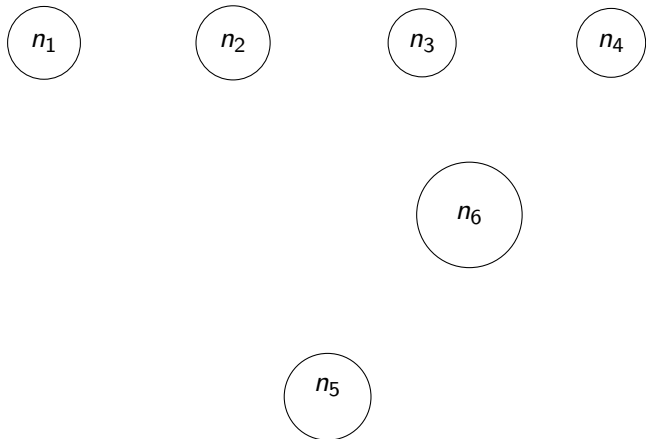
Our approach: (O)PRA

- ▶ the comparison of paths and the use of data values,
- ▶ aggregation of data values along paths,
- ▶ computation of extremal values among aggregated data.
- ▶ modular structure (views/ontologies),
- ▶ good expressive power: subsumes earlier approaches,
- ▶ good complexity: PSPACE-complete (combined) and NL-complete (data),

Graph Databases: labellings



Graph Databases: labellings



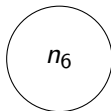
Graph Databases: labellings



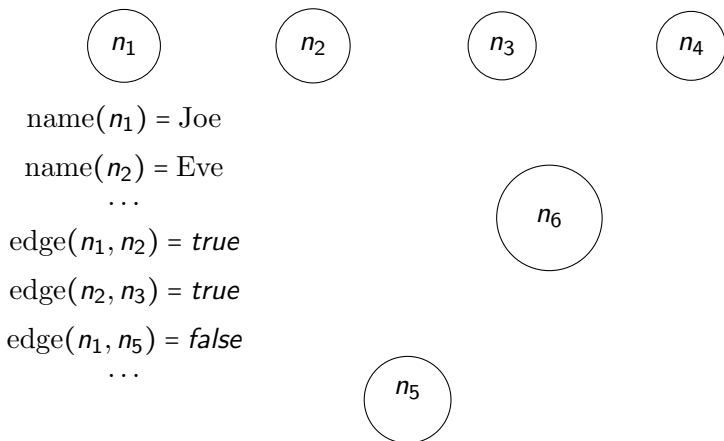
$\text{name}(n_1) = \text{Joe}$

$\text{name}(n_2) = \text{Eve}$

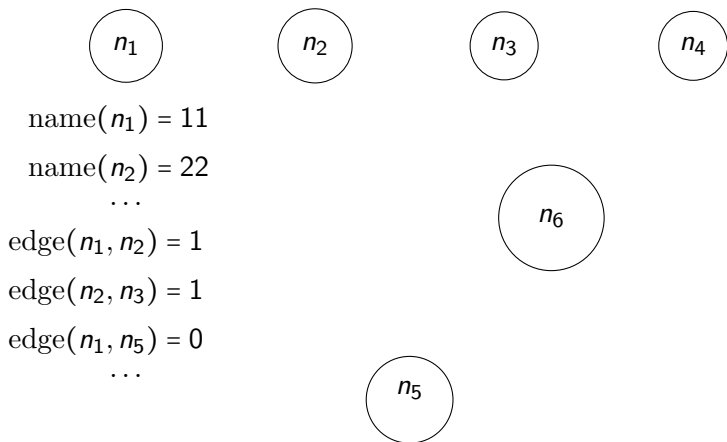
\dots



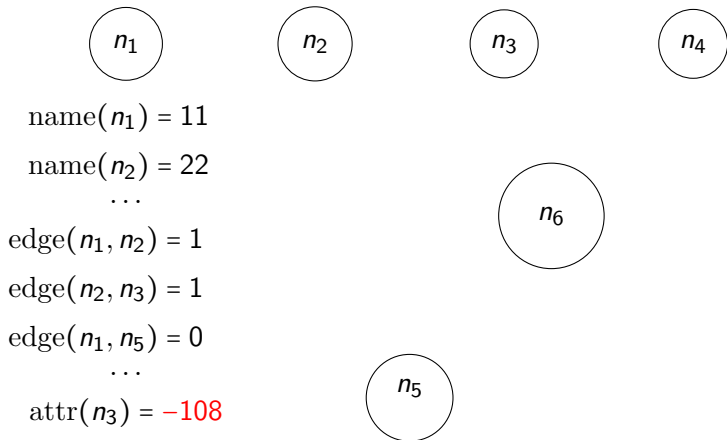
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Building blocks: Node constraints

- ▶ $x \rightarrow^{\pi} y \wedge ((\text{likes} + \text{knows})^* \cdot \text{has})(\pi)$
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 C_1 is the current node,
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 $\langle \text{edge}(\mathbf{C}_1, \mathbf{C}'_1) = 1 \rangle$,
 $\langle \text{type}(\mathbf{C}_1) = 7 \rangle$

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- ▶ In general: $\langle X \leq X' \rangle$, $\langle X < X' \rangle$, $\langle X = X' \rangle$
where X, X' are integer constants or labellings applied to vars (including \mathbf{C}_i).

Building blocks: Regular constraints

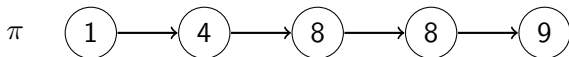
Regular expressions over a path:

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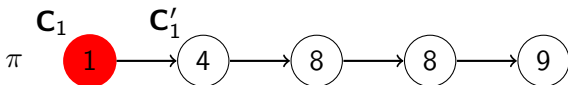
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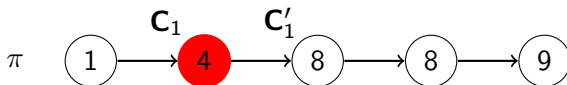
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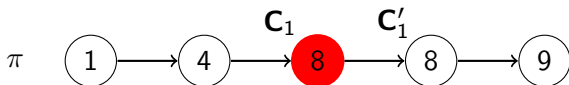
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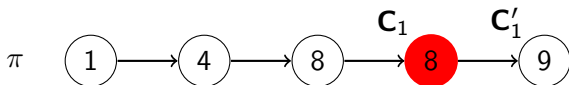
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Regular expressions over a tuple of paths (like in ECRPQs)

- ▶ Here, \mathbf{C}_i is the current node on the i -th path
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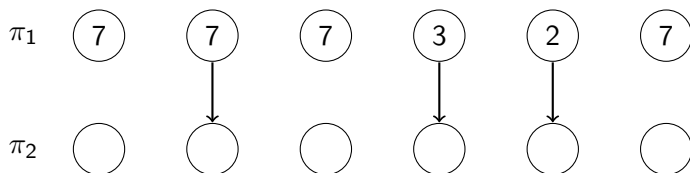
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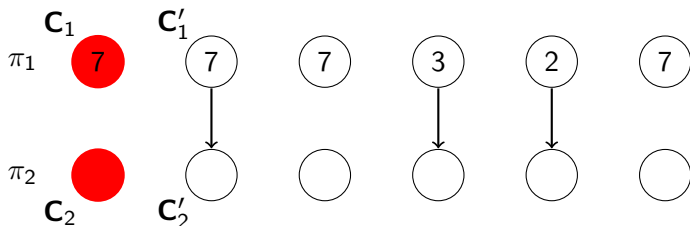
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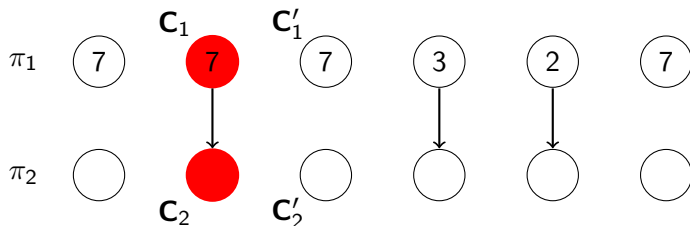
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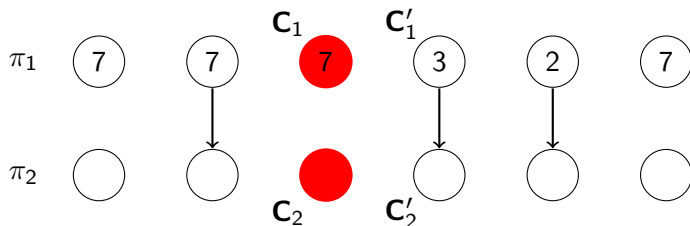
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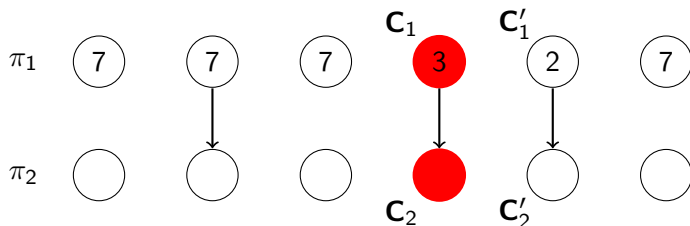
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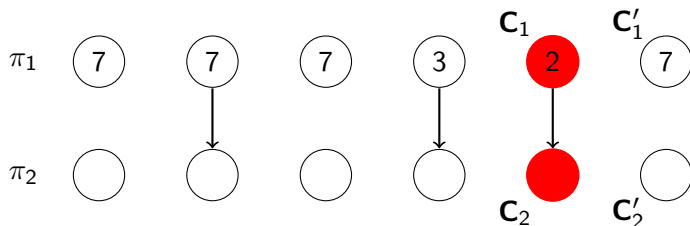
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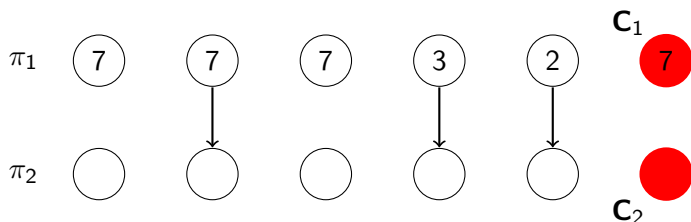
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Building blocks: Arithmetical constraints

Allow to compare boolean combinations of sums along paths:

- ▶ $c_1\Lambda_1 + \dots + c_j\Lambda_j \leq c_0$, where c_i are constants and Λ_j is some labelling $[\pi_{i_1}, \dots, \pi_{i_k}]$.

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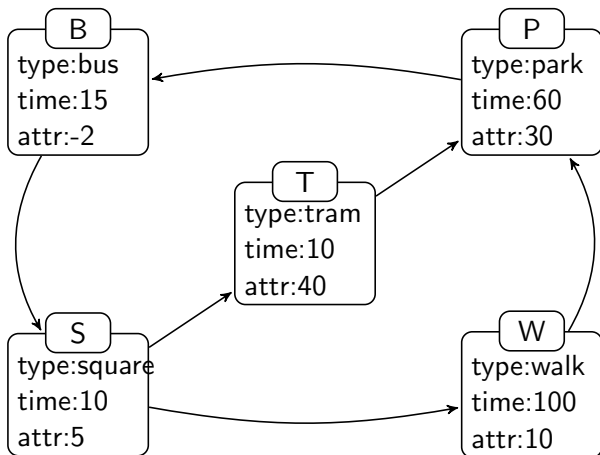
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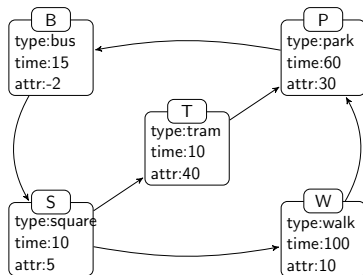
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- ▶ $\text{edge}[\pi_1, \pi_2] \leq 5$ (number of edges between the corresponding places in π_1 and π_2 is ≤ 5).

Example map-representing graph

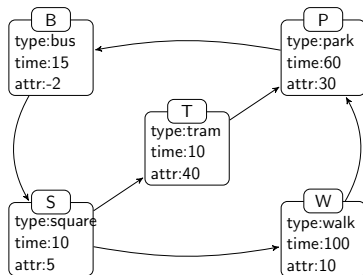


PRA Examples



$$\text{route}(\pi) := \langle \text{edge}(\mathbf{C}_1, \mathbf{C}'_1) = 1 \rangle^* \langle \top \rangle (\pi)$$

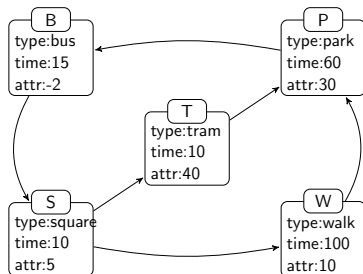
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$\text{route}(\pi) := \langle \text{edge}(\mathbf{C}_1, \mathbf{C}'_1) = 1 \rangle^* \langle \top \rangle (\pi)$

MATCH NODES (s, t) SUCH THAT $s \rightarrow^\pi t$ WHERE $\text{route}(\pi)$
HAVING $\text{time}[\pi] \leq 360 \wedge \text{attr}[\pi] > 100$

PRA Examples



MATCH NODES (s, t) SUCH THAT $s \rightarrow^\pi t$

WHERE $\text{route}(\pi) \wedge \langle \text{type}(\mathbf{C}_1) = c_{\text{tram}} \rangle^*(\rho) \wedge (\langle \text{type}(\mathbf{C}_1) = c_{\text{bus}} \rangle + \langle \text{type}(\mathbf{C}_1) = c_{\text{walk}} \rangle + \langle \text{type}(\mathbf{C}_1) = c_{\text{tram}} \rangle + \langle \text{edge}(\mathbf{C}_1, \mathbf{C}_2) = 1 \rangle)^*(\pi, \rho)$

OPRA: defining new labellings

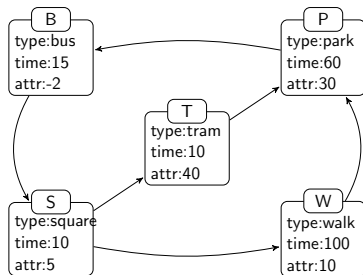
Values for new labellings are specified with *terms*.

$$t(\vec{x}) ::= c \mid \lambda(\vec{y}) \mid [Q(\vec{y})] \mid \min_{\lambda, \pi} Q(\vec{y}, \pi) \mid \max_{\lambda, \pi} Q(\vec{y}, \pi) \\ \mid y = y \mid f(t(\vec{y}), \dots, t(\vec{y})) \mid f'(\{t(x): t(x, \vec{y})\})$$

where $f, f' \in \{\text{MAX}, \text{MIN}, \text{COUNT}, \text{SUM}, +, -, \cdot, \leq\}$ (assuming 0 for false and 1 for true)

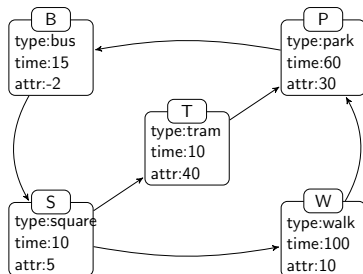
Then, we may write LET $\lambda_1 := t_1, \dots, \lambda_n := t_n$ IN Q .

OPRA Example: new labelling



LET walk_time(x) :=
(type(x) = c_{walk}) · time(x) IN
MATCH NODES (s, t) SUCH THAT $s \rightarrow^{\pi} t$
WHERE route(π) HAVING walk_time[π] ≤ 10

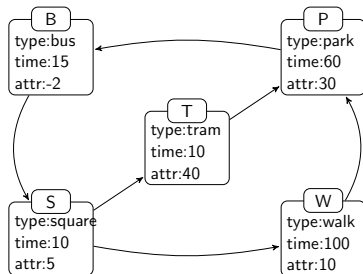
OPRA Example: nested query



LET crowded(x) :=

[MATCH NODES (x) SUCH THAT $x \rightarrow^\pi y$ WHERE
route(π) \wedge $\langle T \rangle^* \langle \text{attr}(\mathbf{C}_1) > 100 \rangle (\pi)$ HAVING time[π] ≤ 10] IN
MATCH PATHS (π) WHERE route(π) \wedge $\langle \text{crowded}(\mathbf{C}_1) = 0 \rangle^* (\pi)$

OPRA Example: most attractive but in minimum time



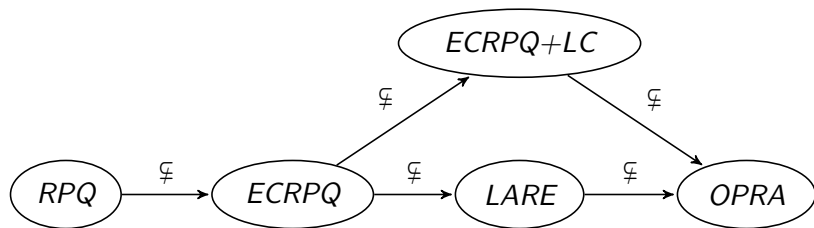
MATCH NODES (s, t) SUCH THAT $s \rightarrow^\pi t$ WHERE $\text{route}(\pi)$
HAVING

$$(\text{attr}[\pi] = \max_{\text{attr}, \rho} Q_{\text{route}}(s, t, \rho)) \wedge$$

$$(\text{time}[\pi] = \min_{\text{time}, \rho} Q_{\text{route}}(s, t, \rho))$$

Our results

Theorem (Expressivity)



Theorem (Complexity)

Query answering for OPRA is PSPACE-complete (combined complexity) and NL-complete (data complexity).